iRobot

The robot for infantry missions

Available now for deployment to today's infantry

Why XM1216 SUGV?

- Meets the demanding requirements of infantry missions
- Lightweight and compact, fits in a MOLLE pack
- Ideal as a point man and forward observer
- Wearable controller and heads-up display ideal for patrols and dismounted operations
- Game-style hand controller reduces training time
- Easily climbs stairs and overcomes obstacles
- Thermal camera captures monochrome images in the dark and through smoke, fog and battlefield obscurants
- 312x optical zoom camera enables day and night surveillance
- Two-way audio provides downrange communication
- Laser rangefinder determines the distance to targets of interest
- Modular design accommodates optional sensors and payloads, including a dexterous manipulator



The advanced wearable controller and heads-up display are ideal for dismounted operations.



U.S. Army Test Center, Aberdeen Proving Ground, *Maryland*

- Environmental Qualification
- Performance Characterization
- System Reliability Assessment

White Sands Missile Range, New Mexico

System Operational Assessment







What people are saying about XM1216 SUGV

"SUGV is probably the best [equipment] of the CP 11 that we have. [It] gives us a better stand-off to actually see what's coming up ahead rather than put actual soldiers up in the front and be surprised. The SUGV actually does save lives."

— Sgt. 1st Class Jason Ramsay of Scout Platoon Headquarters Company, 2nd Infantry Battalion in army.mil

[T]he SUGV was dropped into a concrete tunnel about 20 feet deep. It maintained its link to its operator... and that, one of the soldiers said, was what it was all about. He wouldn't have to crawl through a tunnel with his 9mm pistol in hand, hoping there weren't any booby traps or insurgents waiting for him as he had to do in Iraq.

— DOD Buzz, 9/20/2010

XM1216 SUGV

The robot for demanding infantry missions

Adaptable and expandable, XM1216 SUGV accommodates a wide range of optional payloads and sensors, including a dexterous manipulator. XM1216 SUGV is available with multiple controller options, including wearable controllers, heads-up displays and game-style hand controllers that are ideal for dismounted mobile operations.

Robot **Specifications Robot Dimensions**

Mobility

Cameras and

TIODOL DIIIIOIIOIOIIO	
Height	6.5" (16.5 cm) chassis height when stowed 26" (66 cm) fully extended
Width	• 13.7" (34.8 cm) without flippers • 17.2" (43.7 cm) with flippers
Length	• 23.9" (60.7 cm) with flippers stowed • 30" (76.1 cm) with flippers extended
Weight	• 32 lbs (14.5 kg) with no payloads

Illumination and other sensors

Chassis Camera	Wide angle, fixed focus used for
	driving and stair climbing
	 Resolution: 640 x 480
	 Field of view: 107°
	Responds to IR Illumination
Color Zoom	• Sony 980
Camera	• Zoom: 312x
	(26x optical / 12x digital)
	Resolution: 640 x 480
	• FOV: 42° to 1.6°
	 Auto focus / auto iris
	 Low light capable
	Additional controls: shutter, focu
	Responds to IR Illumination

• 6.2 mph (10 km/h)	
30% (17 deg) lateral84% (40 deg) climb (friction dependent)	**
• 12" (30.5 cm)	
Rise 8" (20.3 cm)Run 10" (25.4 cm)	
• 6" (15.2 cm)	La
	 30% (17 deg) lateral 84% (40 deg) climb (friction dependent) 12" (30.5 cm) Rise 8" (20.3 cm) Run 10" (25.4 cm)

Drive Camera	In head
	Same specs as Chassis Camer
Thermal Camera	Zoom: 3 step digital zoom
	Resolution: 320 x 240
	• F0V: 50°
***************************************	Fixed focus
Illumination	• IR
GPS	• COTS
Laser Range Finder	Range: 1 km

Wireless Range (LOS)	• 3280' (1000 m)
Radio Frequency	2.4 GHz / 4.9 GHz COTS Modular radio interface accommodates future radio upgrades

Neck	Extension: 20" (51 cm)
(True Pan / Tilt)	Degrees of Freedom (DoF):
	 Shoulder: 180° Pitch

· Wavelength: 1550 nm

· Invisible to naked eye

· Invisible to NV goggles

· Class 1 eye safe

2-way Audio • Speaker / microphone in head

• Tilt 1: +/- 180° Pitch

• Pan: 360° continuous rotation

• Tilt 2: +/- 180° Pitch

Design and Construction

Size:	Fits within one standard MOLLE or ALICE pack
Power Source	• 2 BB-2590/U Batteries — more
	than 6 hours of operation
	Tool-less battery installation / removal
Payload Interface	Interface for manipulator and fiber optic spooler
Maintainability	Easy field maintenance LRU strategy



Controller **Specifications**

Choose either a basic or advanced wearable controller:

BASIC Wearable Controller

 Weight: 6 lbs (2.7 kg) Display: Tac-Eye™ heads-up glasses

 Resolution: SVGA (852 x 600) · Sunlight readable

· Controller: game-style hand controller

Advanced Wearable Controller

• Weight: 14 lbs (6.4 kg)

 Display: Tac-Eye™ heads-up glasses

• Resolution: SVGA (852 x 600)

· Sunlight readable

· Rugged hand controller Noise reducing headset

Camelbak® enclosure

These additional options are also available

Heads-Down Rugged Controller • 5.6" LCD display screen

• Resolution: WXGA (1280 x 800)

Sunlight readable

Joystick-style control

Monitor Display

• Weight: 1 lb, 1 oz. (0.482 kg)

• Display: 5.6" (14.2 cm) diagonal screen size

· Resolution: NTSC: (960 x 234) / PAL: (960 x 276)

For indoor use

 Rugged or non-rugged hand controller

Optional Manipulator

Exteriorn.	24 (01 011)
Lifting capacity:	7 lbs (3.2 kg) fully extended15 lbs (6.8 kg) close-in
Degrees of Freedom (DoF):	 Shoulder: 180° Pitch Elbow: +/- 180° Pitch Wrist: 360° continuous rotation
Gripper:	5" (12.7 cm) parallel jaw opening35 lbs (15.9 kg) grip strength
Camera:	Wide angle, fixed focusField of View: 100°

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